UNIVERSITY OF DEBRECEN  
FACULTY OF ENGINEERING

ELECTRICAL ENGINEERING AND MECHATRONICS CONFERENCE EEMC’18

Thursday, 22th of March 2018

Location: Faculty of Engineering, 4028 Debrecen, Ótmető u. 2-4.  
Lecture hall U 003

Conference Chairman: Dr. Géza HUSI

PROGRAM:

09:00 – Opening

PLENARY SESSION (Lecture hall U 003)

Chairman: Dr. Géza HUSI (University of Debrecen, Hungary)

09:00 - 09:30: Dr. Sahin YILDIRIM (Turkey): Design of Neural Predictor for Performance Analysis of Mountain Bicycles.

09:30 - 10:00: Dr. Csaba SZÁSZ (Romania): Last Generation Mechatronics: a Two-level Platform-based Reconfigurable Technology Approach.

10:00 - 10:20: COFFEE BREAK

I. LAST GENERATION OF MECHATRONIC SESSION (Lecture hall U 003)

Chairman: Dr. Géza HUSI (University of Debrecen, Hungary)

10:20 - 10:40: Ammar ALSABBAGH (Syria), Abdulkader BAKI (Syria): Brushless DC Motor Modeling Using Bond Graph Method and Control using LabVIEW.


11:00 - 11:20: Florin Avram, Flaviu Birouas, Vlad Mihalca, Arnold Nilgesz (Romania): Issues regarding management of machining tools, parts and sub-assemblies in flexible manufacturing cells.


11:40 – 13:00: Lunch Break

II. REVIEW ABOUT RESEARCH WORK IN ORADEA SESSION (Lecture hall U 003)

Chairman: Dr. Tibor VESSELÉNYI (University of Oradea, Romania)


13:40 – 14:00: Arnöl Nilgesz, Flaviu Birouas, Florin Avram, Vlad Mihalca (Romania): A review regarding vegetation indices and their validation process.

14:00 – 14:20: Florin Avram, Flaviu Birouas, Vlad Mihalca, Arnold Nilgesz (Romania): Issues regarding management of machining tools, parts and sub-assemblies in flexible manufacturing cells.

14:20 – 14:40: COFFEE BREAK

POSTER SESSION (Lecture hall U 003)

Chairman: Timotei István ERDEI (University of Debrecen, Hungary)

14:40 – 15:40:

- Bence KOVÁCS (Hungary): Intelligent Houses.
- Ammar ALSABBAGH (Syria): Integral LQR-Based 6DoFs Autonomous Quadrocopter Balancing System Control.
- Abdulkader BAKI (Syria): Developing a laboratory Robot Arm using Optimal control.
- Gyula KORSOVECZKI (Hungary): The maintenance, commissioning of FANUC M-1iA 0.5A type selecting robot and implementation of iVision picture-recognizing procedure.
- Aram NASSER (Syria): The goal following robot.
- Bence VADNAI (Hungary): Raspberry PI Cloud service.
- Andor NAGY (Hungary): Data analysis of modern electronic underground railroad vehicle event recorders.
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**PROGRAM:**

**PLENARY SESSION** (Lecture hall U 003)

Chairman: Dr. Péter Tamás SZEMES (University of Debrecen, Hungary)

09:00 - 09:20: Syeda Adila AFGHAN (Pakistan): Lightweight multi-agent framework for a cluster-based wireless sensor network.

**III. MECHATRONICS TODAY SESSION** (Lecture hall U 003)

Chairman: Emese SARVAJCZ-BÁNÓCZY (University of Debrecen, Hungary)

09:20 – 09:40: Hassan Muhammad SHAIKH (Pakistan), Syeda Adila AFGHAN (Pakistan): Reviewing the Power Management IC (PMIC) based on Energy Harvesting.

09:40 – 10:00: Dániel SALÁNKI (Hungary): Development of Gait Recognition in NI LabVIEW.


10:20 – 10:40: COFFEE BREAK

**IV. MODELLING AND SIMULATION SESSION** (Lecture hall U 003)

Chairman: Almusawi Husam ABDULKAREEM (University of Debrecen, Hungary)

10:40 – 11:00: Ahmet Mehmet KARADENIZ (Turkey): Modelling and Simulation of Stepper Motor Using Labview.


11:40 – 12:00: Bence KOVÁCS (Hungary): Smart Home.

12:00 – 12:20: Zsolt TYUKODI (Hungary): Creating GUI for building energy simulation.


12:40 – 13:00: Miklós KUCZMANN (Hungary): Analysis of an induction machine by the finite element method.

13:00 - LUNCH